1. Don’t connect the TX and RX of ultrasonic in reverse.
2. Tear off the sticker of buzzer, longest pin is connected to S, short pin is connected to GND.
3. [Pay attention to the calibration of servos.](https://www.ottodiy.com/blog/calibration)
4. The connection for battery case and switch. The switch has 3 pins. Separately weld the red wire of battery case to the first and the third pin of switch. Another end of red wire is connected to VIN of shield, black wire to GND.
5. More reference for [Arduino IDE](http://wiki.keyestudio.com/index.php/How_to_Download_Arduino_IDE), Arduino [driver](http://wiki.keyestudio.com/index.php/How_to_Install_Arduino_Driver) and [libraries](http://wiki.keyestudio.com/index.php/How_to_Install_Arduino_Library).
6. [Nano driver installation](http://wiki.keyestudio.com/index.php/Ks0173_keyestudio_Nano_ch340)